DOI: http://doi.org/10.32792/utq.jceps.12.02.18

Eye Movement Recognition Using Support Vector Machine

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Abstract:

People with disabilities suffer from inability to communicate with their surroundings, so Human-Computer Interaction (HCI) technologies are used to have a means of communication for people with disabilities with their surroundings. HCI is an emerging technology in the disciplines of Artificial Intelligence and Biomedical Engineering. To power an external device, HCI technology uses several basic signals such as ECG, EMG, and EEG. Electrooculography (EOG) is a technique for measuring the potential difference between the cornea and the retina located between the front and back of the human eye, and the main application of EOG is to determine the directions of different eye movements. This study aims to assess eye movement for communication by persons with disabilities using electrocardiogram (EOG) data. In this study, the Supporting Vector Machine (SVM) classification technique was used and two types of features (statistical and time domain features) were used. Classification accuracy was 90.7% and 93.9% when using SVM with statistical domain and time domain features, respectively

Keyword: EOG, Eye Movement and SVM

1. Introduction:

In recent years ,various bio-signals have worked with technology based on the Human Computer Interface (HCI) [1,2]. Motor neuron deficiencies can result from diseases including amyotrophic lateral sclerosis, spinal cord damage, and others, making it harder to control limb motions. Through the use and implementation of computer-based human rehabilitation aids through various bio-signal modalities, where an EOG is an effective method, HCI technology can help in restoring the activities of a lost or damaged body part by providing a motor, sensory, or cognitive modality [1]. It's non-invasive, affordable, simple to obtain, and may be treated in real time. Eye movement has been shown to have a linear relationship with EOG amplitude to a certain extent. Neuroprosthetic devices [2], computer cursor movement control [3], and rehabilitation wheelchair system control can all benefit from EOG-based device control[4]. Various ways for assessing and implementing EOG for controlling were used [5,6,7,8,9] The EOG has proven to be the most straightforward method for determining eye movement directions. EOG systems with surface electrodes around the orifice are simple to build and alter in real time. The EOG method enables us to forecast the existence of disease in a simple and cost-effective manner, with the symptoms of which being uniquely described by eye movements [10]. The EOG is a

good alternative to hand gestures and speech for HCI. EOG signals are commonly employed in Human-Machine Interface (HMI) applications such as computer control and wheelchairs, as these programs allow individuals with impairments to navigate and manage their computer applications [11]. As a result, the EOG is a good candidate for being used as an eye movement input. The main objective of this research is to evaluate and contrast the accuracy of classification and training duration of Supporting Vector Machine (SVM) classifiers for horizontal eye motions (right and left). The approaches for extracting EOG signals are also examined in this study (statistical features and time domain features).

2. Related Work

Lim Jia Qi(2018) proposed a study to evaluate and compare the performance of different classes (ANN and SVM) in terms of classification accuracy and training time. He also compared three types of features (statistical features, AR coefficients derived from Borg method, PSD estimation using Yule-Walker method). The researcher found that the combination of statistical feature extraction method and SVM is better than using ANN as a classifier 69.75% and less training time [12].

Geer Teng, Yue He, Hengjun Zhao, Dunhu Liu, Jin Xiao, S.Ramkumar (2019) They developed a system that provides nine states of human-computer interface control using EOG signals. Using band power and HHT features and a PRNN classifier, the accuracy of the system was 92.17% and 91.85% using the two types of features, respectively [13].

Ihsan Al-Kabeer, Faisal bin Shaheen and Muhammad Kafiol Al-Islam (2020) developed a system to extract the EOG signal through the different movements of the eyes and use it to control the computer cursor, through the use of machine learning algorithms such as (SVM, MLP) to classify the different patterns resulting from eye movement. The classification accuracy of the system was 80% when using MLP, 93% when using SVM [14].

Thibhika Ravichandran, Nidal Kamel ,Abdulhakim A. Al-Ezzi ,Khaled Alsaih ,Norashikin Yahya(2021) They used EOG signals captured using four sensors placed on the eye movement control muscles in horizontal and vertical directions to classify four different eye movements. The output of the classifier is used to control a wheelchair, or any other device developed to help ALS patients with their daily needs. Where they classified the four movements using two deep learning algorithms (CNN and LSTM). The results showed the relatively better accuracy shown by the CNN model compared to the LSTM model WHITH accuracy of 88.33% for the LSTM network and 90.3% for the CNN network[15].

3. Methodology:

Work is presented to create a system capable of distinguishing horizontal eye movements through EOG signals. The methodology is organized as follows: After the signals are obtained, EOG signal preprocessing, feature extraction, and classification are performed. Finally, the results are compared to see the best performance of the classifier depending on the type of features used with it.

3.1 Data Set:

The usefulness of EOG signals in categorizing horizontal eye movements is being investigated using a publicly available data collection. The EOG Database was employed in this study as the data

source. Electrooculography (EOG) data from six healthy people (2 males and 4 females; mean age 24.73.1 years) is included in this data collection. On a separate cue on the screen, subjects were asked to identify their point of view (POG). A total of four trials were recorded, as shown in Figure 1, in which the subject was requested to complete a goal originating from the center of the screen to a random target location in the first one second. After that, there was a return movement in the following seconds, matching to the middle of the screen, flashing in the last two seconds of each trial Each subject had 300 trials recorded in three consecutive sessions, with 100 trials recorded in each session. Between sessions, there were intermittent pauses. The EOG signals were acquired with a sampling frequency of Fs = 256 Hz using the g.tec g.USBamp bio-signal amplifier device (g.tec medical engineering GmbH, Austria) [16].

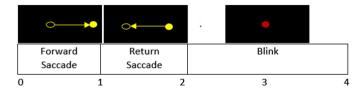


Figure 1: EOG capture session[16].

3.2 signal Preprocessing:

Electrooculography signals are regularly corrupted by noisy Eye blinks, powerline intervention, and other sources of interference, head movements, and so on. A Chebyshev 4th order bandpass filter in that frequency range was utilized because the effective frequency range of EOG signals is between "0.1Hz (DC) and 50Hz". This is done to reduce power supply interference while also suppressing it [17]. Noise was also removed using median filtering. The EOG signal was particularly valuable because it kept Scud's extremely steep character [18].

3.3 Feature extraction:

Feature extraction is a method of extracting important features from the original data without losing important information. This step is used to reduce the size of the data [19]. We employed two feature extraction algorithms in this paper.

3.3.1 Statistical Features:

In this study ten statistical features were extracted to present the characteristic of EOG signal. Those statistical feature are [18]:

- 1. Minimum
- 2. Maximum
- 3. The First Quartile (Q1)
- 4. The Third Quartile (Q3)
- 5. The Interquartile Range (IQR)
- 6. The Mean
- 7. The Mode
- 8. The Median
- 9. Variance (σ^2)

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$$Variance(\sigma^2) = \frac{\sum_{i=1}^{N} (x_i - mean)^2}{N-1}$$
 (1)

Where:

- x_i =Value of the *i*th point in the data set.
- mean =The mean value of the data set.
- N = The number of data point in the data set.

10. Standard Deviation (σ)

Standard Deviation
$$(\sigma) = \sqrt{\frac{\sum_{i=1}^{N} (x_i - mean)^2}{N-1}}$$
 (2)

Where:

- x_i =Value of the *i*th point in the data set.
- *mean* =The mean value of the data set.
- N = The number of data point in the data set.

3.3.2 Time Domain Features:

In this paper, five time domain feature were extracted for EOG signal, these feature with define in were presented as [20]:

- 1. Maximum peak amplitude value: This is a measurement of the EOG signal's amplitude at its highest point, as well as the greatest positive and negative values.
- 2. Maximum valley amplitude value: This is the highest negative value of the EOG signal's amplitude at its lowest point.
- 3. Maximum peak amplitude position value: This is a measurement of the amplitude position value of the EOG signal at its highest point, as well as the maximum positive and negative values.
- 4. Maximum valley amplitude position value: This is the amplitude position value of the EOG signal at its lowest point, with the highest negative value.
- 5. Area Under Curve: AUC of EOG signal is a summation of absolute value of the amplitude under both positive and negative curves in horizontal channel. as shown in Figure 2.

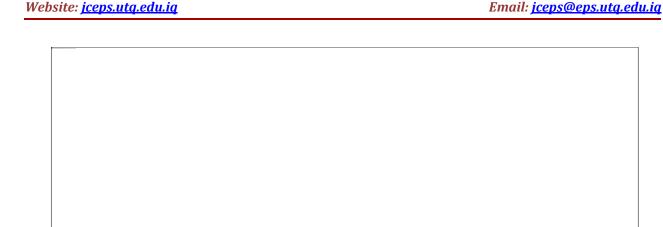


Figure 2: Areas under curve values [19].

4. Classification:

The classification is done using SVM algorithm on the feature set extracted from the raw EOG signal as mentioned before. SVM is a useful classification technique in a variety of disciplines of research. Its applications include text categorization, facial identification, breast cancer diagnosis, and more. SVM is a linear classification method that seeks for the best hyperplane . The term "optimal hyperplane" refers to a linear decision boundary that split N dimensional space (R n) into two halves with resolution limits as far away from both subclasses' data as possible. Because Recession variables and kernel functions have been added, SVM can now be employed in Non-linear detachable situations with high dimensional data entry. In this investigation, The SVM is trained with a paired (feature and class) . Let a training set comprising of N classes with f attributes, the set can be represented by $\{(xi,yi) \mid xi \in R, yi \in \{-1,1\}\}$ where i=(1,...,N) If the input data is linearly distinguishable, the optimization phase can be defined as follows [21]:

Min w,b
$$\|\mathbf{w}\|^2$$
 (3) Where:

 $Yi (w.xi+b) \ge 1$

w: is a weight vector.

b: is the bias term.

the hyperplane is defined by w. x+b=0.

Suppose entity in the testing set is classified using the decision function

$$f(x) = w \cdot x + b \tag{4}$$

Where:

w: is a weight vector. b: is the bias term.

If f(x) < 0. As a result, the instance falls on one side of the hyperplane. However, the entity x is identified and put in the first class (y = -1), otherwise is classified into the second class (y = 1).the Radial Basis Function (RBF) was chosen for classification because it is often used and considered the first choice in literature.

5. Results and discussions:

In this section, we discussed the most important result of this work. For remove noise from the signals as shown in Figure 3, the raw data is filtered with a 0-30 Hz band-pass filter and a 50 Hz average filter to remove noise and other interferences that spoil the regularity of the EOG signals, such as eye blinks, power line interference, head movements, etc.

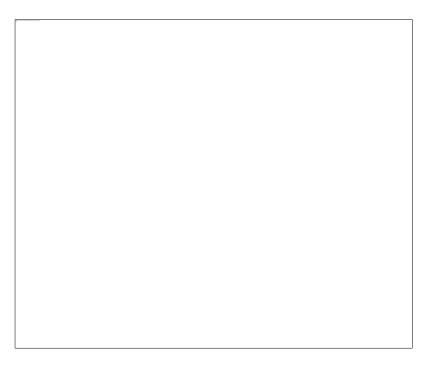


Figure 3: EOG signals before and after preprocessing.

After the noise removal phase, the data set was divided into 70% of the EOG signals as training data while the remaining 30% is used for testing purposes, as these percentages gave the highest classification accuracy. These data produce ten statistical features and five time domain features. Training vectors are used to train the classifier (SVM), while test vectors are used to evaluate the accuracy and usefulness of the learned models.

In the signal classification stage, the SVM classification algorithm was applied with the two types of features that were previously referred to as input data for the classifier. After the classification process was completed, the performance of the SVM classifier was tested according to the test accuracy and training time to evaluate and compare performance. The fraction of actual positives that are expected to be positive is used to assess classification accuracy [22].

Classification accuracy (%) =
$$(TP + TN) / (TP + TN + FP + FN)$$
 (5)

where NT denotes the number of correct predictions and NF denotes Number of times incorrect predictions. Through the results presented in Table 1 and Table 2, And use the same classification method ,A classification accuracy rate was 93.9% and with a low training time it was 5.9 s. All results are shown in Table 1 and 2 . all the result obtained in table 1 and 2 were using SVM classifier , as can be seen in

tables . SVM classifier gave better results when using it with time domain features in terms of classification accuracy rate and training time compared to the results obtained from using it with statistical features. It can be seen from Table 1. On the other hand, the results of the SVM classifier with the statistical parameters as inputs also achieve a high accuracy of 90.7 % and training time of 6.6 s . As shown in Table 3 . Through the obtained results, it was found that the SVM classifier, which represents a supervised learning approach, gives higher classification accuracy when using time domain features with it.

Table 1. Classification results for time domain features with SVM classifier.

Subjects	S1	S2	S3	S4	S5	S6
Classification accuracy (%)	96.3	96.3	94	91.3	91.7	94.3
Training time (s)	5.9	5.9	5.9	5.9	5.9	5.9

Table 2. Classification results for statistical features with SVM classifier.

Subjects	S1	S2	S3	S4	S5	S6
Classification	95.3	93	89.7	87.7	87.7	91
accuracy (%)						
Training time	6.6	6.6	6.6	6.6	6.6	6.6
(s)						

Table 3. Compare the results when using an SVM classifier with two types of feature extraction methods.

Subjects	SVM classifier with time domain feature	SVM classifier with time domain feature
Classification accuracy (%)	93.9	90.7
Training time (s)	5.9	6.6

Website: jceps.utq.edu.iq Email: jceps@eps.utq.edu.iq Figure 4: The process of training data using the SVM classifier with time domain feature.

Figure 5: The process of training data using the SVM classifier with statistical feature.

6. Conclusion:

EOG signals have great potential for use in communications such as eye-controlled wheelchairs and virtual keyboards. In the next classification stage of EOG signals, the features collected from the data set play an important role. This paper looked at various ways to improve the analysis and classification of the EOG signal. The presented approach for extracting time-domain features from the EOG badge showed superiority over the other options (statistical feature set) in terms of classification accuracy and training duration, although the statistical feature set gave high results in terms of accuracy up to 90.7% and little training time, However, it was found that combining the time domain feature extraction method with SVM produces better results, with 93.9 percent classification accuracy and lower training time. Our future plan is to try other methods of classifying signals and extracting features, in order to obtain higher classification accuracy. We also hope to classify additional eye movements in the future.

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